

# Commentary on the use of the reproduction number $R$ during the COVID-19 pandemic

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## Abstract

Since the beginning of the COVID-19 pandemic, the reproduction number  $R$  has become a popular epidemiological metric used by policy makers and the media to communicate the state of the epidemic across countries. At its most basic,  $R$  is defined as the average number of secondary infections caused by one primary infected individual.  $R$  seems convenient and easy to use, because the epidemic is expanding if  $R > 1$  and contracting if  $R < 1$ . The magnitude of  $R$  indicates by how much transmission needs to be reduced to control the epidemic. However, using  $R$  in a naïve way can cause new problems. The reasons for this are threefold. 1) There is not just one definition of  $R$  but many, and the precise definition of  $R$  affects both its estimated value and how it should be interpreted. 2) Even with a particular clearly defined  $R$ , there may be different statistical methods used to estimate its value, and the choice of method will affect the estimate. 3) The availability and type of data used to estimate  $R$  vary, and it is not always clear what data should be included in the estimation. For example, should imported cases that are immediately quarantined count towards  $R$ , or should the data used to estimate  $R$  capture the potential of the local population to transmit the infection? In this review, we discuss when  $R$  is useful, when it may be of use but needs to be interpreted with care, and when it may be an inappropriate indicator of the progress of the epidemic. We also argue that careful definition of  $R$ , and the data and methods used to estimate it, can make  $R$  a more useful metric for future management of the epidemic.

## 1 What is the reproduction number $R$ ?

Since the start of the novel coronavirus (SARS-CoV-2) pandemic, the reproduction number  $R$  has become a popular summary statistic, used by policy makers to assess

31 the state of the epidemic and the efficacy of interventions and by the media to  
32 communicate the progress of the epidemic to the general public. The primary appeal  
33 of  $R$  is that it offers a single number that indicates whether the transmission of the  
34 pathogen is increasing or decreasing, depending on whether  $R$  is above or below  
35 one. Early  $R$  estimates for SARS-CoV-2 in different countries were in the range  
36 of 2.0 - 6.5 [34, 52]. However, the use of  $R$  can be problematic in terms of both  
37 its definition and its estimation. Its usefulness is precisely because it is a summary  
38 statistic rather than a basic parameter describing the dynamic processes of infection,  
39 transmission and recovery. To understand how it is calculated and how it can be  
40 affected by interventions, the epidemic process needs to be considered in more detail.  
41 When epidemic numbers are small or concentrated in possibly atypical parts of a  
42 population, it may be an unreliable descriptor of the state of the outbreak.

43 In this paper, we discuss these issues and determine the situations when  
44 the reproduction number  $R$  is most useful for assessing and communicating the state  
45 of an outbreak (see Figure 1).

## 46 1.1 The beginning of a pandemic - $R_0$

47 In the early stages of a new outbreak of an infectious disease we can define an  
48 initial  $R$  value, known as the *basic reproduction number*  $R_0$ , that is the average  
49 number of individuals infected by each infectious individual in a fully susceptible  
50 population [21, 30, 31]. An outbreak resulting from one infected individual may die  
51 out within a few infection generations by chance. Otherwise, if  $R_0 > 1$ , the incidence  
52 of cases will grow exponentially, with on average  $R_0^n$  cases in the  $n^{\text{th}}$  generation.  
53 Already, this simple description introduces a number of concepts and assumptions.  
54 An individual's *infection generation* specifies their position in the chain of infections,  
55 the  $(n - 1)^{\text{th}}$  generation infects the  $n^{\text{th}}$  generation, and so on. It also assumes an  
56 underlying scenario (model) in which the average number of susceptibles infected by  
57 each infective stays the same over successive infection generations, and ignores the  
58 depletion of susceptibles. (We refer to those members of the population who are  
59 uninfected and susceptible to infection as *susceptibles*, and those that are infected  
60 and infectious as *infectives*.) The potential importance of these assumptions depends  
61 on the contact structure of the population, to which we return below.

62 Thus,  $R_0$  (and other  $R$  values to be defined later) is not just a property of  
63 the infectious agent (*pathogen*). It depends on demography, and whatever human  
64 behaviour is associated with the possibility of infectious contact (an *effective contact*  
65 is one that results in transmission if made with a susceptible, while a contact in  
66 the common sense of the word has a certain probability of transmission). For the  
67 simplest models,  $R_0 > 1$  implies that an introduction of infection will result in an  
68 epidemic. Furthermore, if there were no interventions or changes in behaviour, then  
69 the proportion of the population infected during the entire course of an epidemic

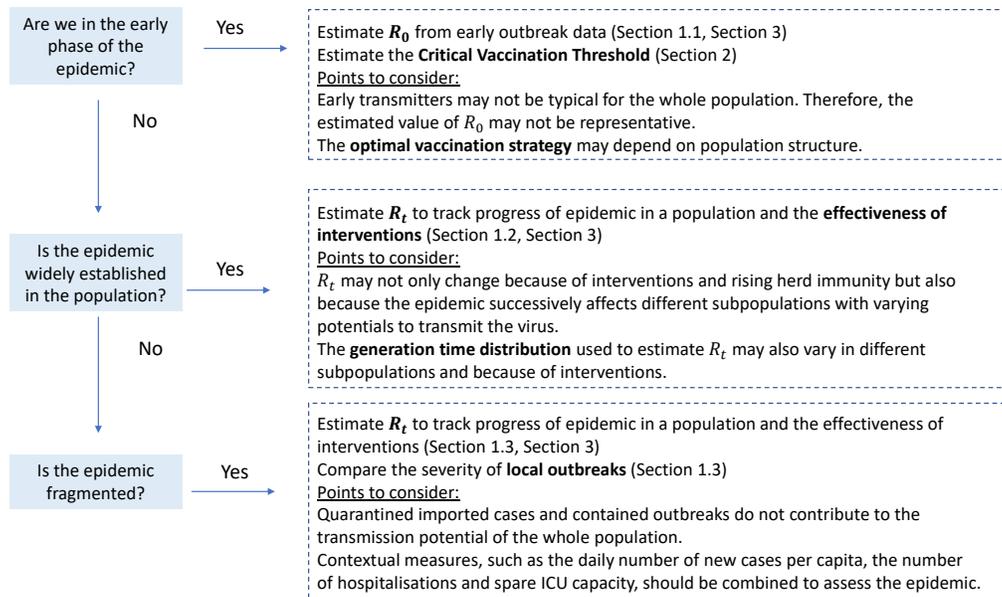


Figure 1: Flow chart summarising the main points explained in the main text depending on the state of the epidemic

70 would be the non-zero solution of the equation  $P = 1 - e^{-R_0 P}$  (for example, if  
 71  $R_0 = 2$ , then  $P$  is approximately 0.8). This result is referred to as the *final size*  
 72 *equation*, and underscores the fact that during an epidemic it is not generally true  
 73 that everybody will be infected at some point.

74 Individuals may vary considerably in their susceptibility to infection and  
 75 in their propensity to pass it on through their biology or behaviour. Age is often  
 76 an important determinant. If the population is grouped in some way, so that for  
 77 instance some groups have higher  $R$  values than others, then the overall outbreak  
 78 is expected to grow as described by an  $R_0$  that depends on all of these values, and  
 79 also depends on how each group infects the others, i.e. on the  $R$  values between  
 80 groups as well as within them ( $R_0$  is then the dominant eigenvalue of the matrix of  
 81  $R$  values [20,21,30]). The first few stages of the outbreak may be atypical, depending  
 82 on which group is first infected.

83 For the simplest mathematical model of the beginning of an outbreak, it  
 84 is assumed that because only a small fraction of the population has been infected,  
 85 all potential contacts are with susceptibles. This may be an unrealistic assumption  
 86 because human interaction networks tend to be clustered (for example, through  
 87 households, workplaces or schools). Growth through successive generations of infection,  
 88 which is the basis for defining  $R_0$ , does not translate simply into time, because  
 89 the *generation interval* of an infection (the time interval back from the instant when  
 90 a susceptible is infected, to that when their infector was infected) is variable, and  
 91 infection generations may overlap temporally. Typically, growth in the early stages

92 is faster than the simple assumption of a fixed average generation time would suggest  
93 and this is a major problem in estimating  $R_0$  from early outbreak data. In addition,  
94 the implicit assumption is that all infectives are identifiable as such. If there is a  
95 significant proportion of asymptomatic cases, an estimate of  $R_0$  may be affected by  
96 the time from when an asymptomatic infective has become infected to when he/she  
97 is expected to infect susceptibles. If this timing is the same for asymptomatic and  
98 symptomatic cases, then the estimate for  $R_0$  will be unaffected.

## 99 **1.2 The second simplest case: where an outbreak is widespread** 100 **- $R_t$**

101 When the pandemic is well-established in a country (or region), with large numbers  
102 of cases most of which are internal to the country, an ‘effective reproduction number’  
103 at time  $t$ ,  $R_t$  (sometimes denoted  $R_e$  or  $R_{eff}$ ), is a useful descriptor of the progress  
104 of the outbreak (Figure 1). Again, the concept is of an average of how many new  
105 cases each infectious case causes. The value of  $R_t$  may be affected by interventions:  
106 typically the aim is to reduce  $R_t$  below one and to as small a value as possible. For  
107 models including detailed, and therefore complex, contact networks there may be  
108 more than one way of defining  $R_t$ ; however, definitions should always agree that the  
109 value of  $R_t$  is 1 when the expected number of new infections is constant.

110 The relevance of the assumptions here (large numbers of cases, mostly in-  
111 ternal to the region) is that in such circumstances we expect  $R_t$  to have a fairly stable  
112 value that changes substantially over time only when interventions are introduced  
113 or cease. The definition of  $R_t$  here is in terms of actual new infectious cases, i.e.  
114 excluding potentially infectious contacts with individuals who have had the disease  
115 and are immune to reinfection. As the number of immune individuals grows large  
116 compared to the entire population, the spread of infections will gradually slow, be-  
117 cause many contacts will be with immune individuals, and hence the value of  $R_t$  will  
118 be reduced. The level of immunity at which  $R_t = 1$  is the *herd immunity threshold*  
119 (see Section 2 on vaccination and herd immunity below).

## 120 **1.3 When the outbreak is at a low level or fragmented – the** 121 **concept of $R$ may be less useful**

122 If the outbreak is at a low level either because it has run its course or because of suc-  
123 cessful interventions, the definition and the use of an  $R$  value are problematic (Figure  
124 1). At low levels of prevalence there will (as in the early stages of the outbreak) be  
125 greater statistical variability. Additionally, there are likely to be heterogeneities as-  
126 sociated with the infection being unevenly spread among different subgroups of the  
127 population (possibly dependent on age, behaviour or geographical location [53]), with

128 some parts of the population having had more exposure than others. There may also  
129 be local variability in interventions, and it may not be easy to allow for the effect of  
130 some cases being introductions from outside the population under consideration. If  
131 the outbreak is fragmented, particularly when close to elimination, it will make more  
132 sense to think of it as composed of separate local outbreaks, which can be modelled  
133 separately, rather than trying to specify an average  $R$  value overall.

## 134 1.4 Relating $R$ to details of the infection process

135 If the population is heterogeneous or structured, defining a reproduction number  
136 needs care, as the number of new cases an infective is expected to cause will depend on  
137 both their infectiousness and how well connected they are. It has been shown that in  
138 the early stages of an epidemic, when the relevant contact structures of a population  
139 are not known and interventions are not targeted, assuming a homogeneous contact  
140 structure results in conservative estimates of  $R_0$  and the required control effort.  
141 However, designing targeted intervention strategies requires reliable information on  
142 infectious contact structures [?]. There are several basic ways to use structured  
143 population models to capture departures from the simplest epidemic models. The  
144 four most common are (i) household models, (ii) multi-type models, (iii) network  
145 models and (iv) spatial models.

146 In a household model, every person in the population is assumed to be  
147 part of a single household, which is typically small, and may even be of size one.  
148 Those in the same household have a higher probability of infecting each other than  
149 is the case for two people chosen randomly from the population. In this model,  
150 reproduction numbers can still be defined [6, 26]. The most commonly used is the  
151 household reproduction number  $R_*$ , which is the expected number of members of  
152 other households that are infected by people from a primary infected household. It  
153 is still possible to consider the average number of susceptibles infected by a single  
154 infectious person. However, in order for this to be useful, the average has to be  
155 computed in a sophisticated way, because the number of people a person can infect  
156 will depend on how many members of the same household are still susceptible when  
157 s/he becomes infectious [46].

158 A second way of modelling heterogeneity in the population is to assume that  
159 the population can be subdivided into groups. The groups may be defined through  
160 age bands, social activity levels, health status, type of job, place of residence and  
161 so on. Characteristics such as susceptibility, infectivity and frequency of contact  
162 may depend on an individual's group, but all those in a single group have the same  
163 characteristics. It is often assumed that all these groups are large. If there are regu-  
164 lar inter-group contacts then the largest eigenvalue of the so-called next generation  
165 matrix [20, 21] has many similar properties to those of  $R_0$  for an epidemic spreading  
166 in a homogeneously mixing population, although the final size equation is generally

167 not satisfied.

168 A third way of introducing heterogeneity is to represent the population by  
169 a network, where transmission is only possible between people sharing a link in the  
170 network. For many network models it is still possible to define a reproduction number  
171 [36]. It is important to note that the person initially infected in a population is often  
172 atypical and should be ignored in computing or estimating the reproduction number.  
173 A useful extension is a mixture of a network model and a homogeneous mixing  
174 model, in which both regular and casual contacts are captured. In this extension, a  
175 reproduction number with the desired threshold properties can be defined [5].

176 Sometimes most transmission is restricted to people living close to each  
177 other, and spatial models are useful when physical location should be incorporated.  
178 For these, it is often difficult to define a reproduction number because there is no  
179 phase in which the number of infecteds is growing exponentially [19,47]. If standard  
180 estimation methods are used where there is a considerable spatial component then  
181 the estimates will be close to one, even when the spread is highly supercritical and  
182 transmission needs to be much reduced in order to control the epidemic.

## 183 **2 $R$ , vaccination and herd immunity**

184 As immunity builds up in a population through infection during the course of an epi-  
185 demic, even when the contact rate between individuals remains the same (assuming  
186 no change in interventions), both the chance that a contact is susceptible to infection,  
187 and the effective reproduction number,  $R_t$ , will decrease. Herd immunity is achieved  
188 when enough individuals have become immune so that  $R_t$  falls below the value 1  
189 without the need to reduce contacts among individuals by non-pharmaceutical in-  
190 terventions.

191 Vaccination provides another means of building up immunity in a popu-  
192 lation. Depending on the coverage, it can slow or halt the spread of an epidemic,  
193 preventing individual infection or limiting experiences of disease. All vaccination  
194 programs aim to achieve sufficient immunity in the population that  $R_t < 1$  without  
195 modifying contact patterns among individuals. In this situation, there are insuf-  
196 ficient susceptibles in the population for sustained transmission. The susceptible  
197 proportion of a population for which  $R_t = 1$  is known as the *critical vaccination*  
198 *threshold (CVT)*. When the susceptible proportion is below this threshold, there is  
199 herd immunity, which means that the population is protected from a major outbreak  
200 even though not everyone is vaccinated or otherwise immune.

201 In simple mathematical models (e.g. models in which the population is  
202 only subdivided into susceptible, infected and recovered individuals), the CVT is  
203 determined by the basic reproduction number  $R_0$ . Specifically, vaccination of a

204 uniform randomly chosen proportion  $1 - \frac{1}{R_0}$  of the population is sufficient to create  
205 herd immunity and prevent an epidemic, as long as the vaccine-induced immunity  
206 is sufficiently long-lasting [51]. As a simple example, if  $R_0 = 2$  then 50% of a  
207 population would need to be vaccinated or otherwise immune to prevent outbreaks.  
208 If  $R_0 = 3$ , as is approximately the case for COVID-19, then 67% of a population  
209 would need to be vaccinated or immune. When setting such vaccination targets,  
210 waning immunity needs to be taken into account. The implementation and impact  
211 of a vaccination programme depends on whether vaccination is performed before or  
212 during an outbreak [13, 32].

213 As outlined above, population structure affects the reproduction numbers  
214  $R_0$  and  $R_t$  as well as the probability that an epidemic will spread. Therefore, it has  
215 important effects on the threshold for herd immunity and the optimal vaccination  
216 strategy. For models with small mixing groups such as households, the basic repro-  
217 duction number  $R_0$ , as defined in Section 1.1, does not provide a good indicator of  
218 whether or not an epidemic can take off because repeated contacts within households  
219 are likely even in the early stages of an outbreak. However, in the early stages of an  
220 epidemic, between-household contacts are likely to be with individuals in otherwise  
221 fully susceptible households, so the reproduction number  $R_*$  which is given by the  
222 average number of between-household contacts that emanate from a typical within-  
223 household epidemic [4, 7] can be used instead. For household models, herd immunity  
224 is achieved if a uniform randomly chosen proportion  $1 - \frac{1}{R_*}$  of all *households* in a  
225 population is fully vaccinated.

226 For COVID-19, a toy model has been used to illustrate the effect of popula-  
227 tion heterogeneity on herd immunity. It showed [11] that age structure and variation  
228 in social contacts among individuals could reduce the herd immunity threshold to  
229 43%, almost a third less than that for a homogeneous population. Assuming a more  
230 extreme variation in social contact rates and that the most exposed individuals be-  
231 come infected first, another study estimates that the herd immunity threshold in  
232 some populations could be as low as 20% [28]. In addition, there is some indica-  
233 tion that immunity gained from infection by some common cold coronavirus strains  
234 may provide cross immunity to SARS-COV-2 [49, 58]. There have also been reports  
235 that immunity gained from COVID-19 infection may wane, reducing individual and  
236 population levels of immunity over time. If these observations are indeed applicable  
237 here, the herd immunity threshold could be further modified [49].

238 One important difference between immunisation by vaccination and by in-  
239 fection is that, during an epidemic, individuals with higher susceptibilities and/or  
240 larger numbers of contacts are likely to be infected earlier. If herd immunity is to  
241 be achieved by vaccination, optimal planning can reduce the coverage required to  
242 achieve herd immunity. For example, in an illustrative households model for variola  
243 minor infections in Brazil, it is shown that under the optimal vaccination strategy  
244 the proportion of the population that needs to be vaccinated is a third less than un-  
245 der a strategy that fully vaccinates randomly chosen households [3]. If a COVID-19

246 vaccine is developed, demand will surely exceed supply initially. Designing optimal  
247 vaccination strategies for different settings that take into account population struc-  
248 ture alongside other public health concerns, e.g. protecting the vulnerable, could  
249 greatly enhance the chances of achieving herd immunity and the cost effectiveness of  
250 vaccination as an intervention.

### 251 **3 How can $R$ be estimated?**

252 Before estimating  $R$ , the purpose of the estimation needs to be clarified. Is it intended  
253 simply to track the changes in the trajectory of case numbers over time? Or is it  
254 intended to assess the potential of a population to transmit a pathogen perhaps in  
255 the context of considering interventions? If the latter, the relevant population needs  
256 to be defined. Depending on the purpose, different data sets and statistical methods  
257 can be used.

258 There are several approaches to estimating  $R_t$  from epidemiological data.  
259 In the most direct method, high-quality contact tracing data can be used, in theory  
260 at least, to estimate both  $R_t$  and the generation time interval, and this has been  
261 attempted for COVID-19 [22]. However, contact tracing of SARS-CoV-2 infections  
262 is notoriously difficult because of the high proportion of asymptomatic infections.  
263 Moreover, effective contact tracing reduces the number of contacts of traced individ-  
264 uals so that the corresponding estimates will be biased.

265 More commonly,  $R_t$  can be estimated by inferring the rate of infection  
266 transmission within a dynamical model fitted to observed cases, hospitalisations,  
267 deaths or a combination of those [48, 56]. Dynamical models have been used widely  
268 to forecast the spread of COVID-19 and the effect of interventions. These models  
269 allow the impact of assumed changes in specific interventions on  $R_t$  to be explored, so  
270 estimating  $R_t$  in this way can be convenient. Dynamical models can be described by  
271 systems of differential equations and assume very large to infinite population sizes. In  
272 completely deterministic dynamical models, the uncertainty in estimated  $R_t$  values  
273 depends only on data and parameter uncertainty, and not on stochastic uncertainty.  
274 However, if the number of new infections is small, the value of  $R_t$  is strongly affected  
275 by chance events, which increases the uncertainty in the estimate. This situation can  
276 be addressed by use of stochastic models or incorporating stochastic assumptions in  
277 otherwise deterministic model frameworks.

278 But this approach is not without drawbacks. Not least,  $R_t$  estimates from  
279 dynamical models depend critically on assumptions (e.g. model structure and which  
280 parameter values are estimated), and on data quality. Another potential drawback is  
281 that many parameters of dynamical models are often assumed to be fixed over time.  
282 These approaches are therefore less suited to capture the effects of gradual, contin-  
283 uous changes in behaviour, mobility or social network structure. However, gradual

284 changes in dynamic models can be incorporated by assuming that transmission pa-  
285 rameters change over given intervals, while at the same time the possible amount of  
286 change is constrained to avoid big jumps caused by a small number of noisy data  
287 points [10]. In this way, dynamical models that include change-points in the rate of  
288 infection near specific interventions can infer the impact of control policies, as well  
289 as the effect of susceptible depletion.

290 There is also a difference in how  $R_t$  is estimated between compartmental and  
291 agent- or individual-based models. In an agent-based model, it is possible simply to  
292 count exactly how many secondary infections are caused by each primary infection.  
293 Thus, all details of the epidemic – including time-varying viral loads, population-  
294 level and localised immunity, interventions, network factors, and other effects – are  
295 automatically incorporated, and do not need to be considered separately [44]. As  
296 agent-based models explicitly include stochastic effects, the uncertainty in  $R_t$  esti-  
297 mates can be greater than for those derived from deterministic dynamical models.  
298 Because of the greater number of parameters included in dynamical and particularly  
299 agent-based models, they require more data and more different types of data than  
300 the simpler statistical models below to identify estimates for all parameters.

301 A third approach uses statistical models to estimate  $R_t$ , and continuous  
302 changes in it, empirically from case notification data. These methods make minimal  
303 structural assumptions about epidemic dynamics, and only require users to specify  
304 the distribution of the generation interval. They are agnostic to population suscep-  
305 tibility or epidemic phase, but as we discuss below, care must still be taken to avoid  
306 quantitative and temporal biases. The most common empirical methods are the Cori  
307 method [18, 54] and the Wallinga-Teunis method [57]. Drawbacks of some statistical  
308 models include that they cannot be used to combine different data streams into a  
309 coherent picture.

310 Where genome sequences from viral samples taken from infected patients  
311 are available and the date of sampling is known,  $R_t$  can also be estimated using phy-  
312 logenetic methods. An evolutionary model is fitted that best explains the patterns  
313 of nucleotide substitution in the dated samples. The fitted model parameters in-  
314 clude the nucleotide substitution rate and the population size of the virus at a given  
315 time in the past. Using a metapopulation analogy, the effective population size of  
316 a pathogen has been shown to be proportional to the number of infected individu-  
317 als and inversely proportional to the transmission rate from which the reproduction  
318 number can be determined [38].

### 319 **3.1 Statistical methods to estimate $R$**

320 In this paragraph we discuss two frequently used simple statistical methods to es-  
321 timate  $R$  and common issues associated with them. The Cori and Wallinga-Teunis  
322 methods estimate subtly different versions of  $R_t$ ; the Cori method generates esti-

323 mates of the instantaneous reproduction number and the Wallinga-Teunis method  
324 generates estimates of the case reproduction number [18, 24]. The key difference is  
325 that the instantaneous reproduction number gives an average  $R_t$  for a homogeneous  
326 population at a single point in time, whereas the case reproduction number can ac-  
327 commodate individual heterogeneity, but blurs over several dates of transmission.  
328 Furthermore, the case reproduction number is a leading estimator of the instanta-  
329 neous reproduction number, i.e. it depends on data from after the time for which the  
330 reproduction number is to be estimated, and must be adjusted accurately to infer  
331 the impact of time-specific interventions [29].

332 The instantaneous reproduction number represents the expected number of  
333 infections generated at time  $t$  by currently infectious individuals [18]. For real-time  
334 analysis, one of the benefits of estimating the instantaneous reproduction number is  
335 that it does not require information about future changes in transmissibility, and it  
336 reflects the effectiveness of control measures in place at time  $t$ . But as an aggregate  
337 measure of transmission by all individuals infected in the past (who may now be  
338 shedding virus), it does not easily consider heterogeneity in transmission. In contrast,  
339 the case reproduction number represents the expected number of infections generated  
340 by an individual who is first infected at time  $t$ , and has yet to progress through the full  
341 course of viral shedding. This leads to “right censoring” when the case reproduction  
342 number is estimated in real-time; if all infections generated by individuals who were  
343 infected at time  $t$  have not yet been observed, then the data must be adjusted  
344 [14, 15, 43] or the case reproduction number will be underestimated.

345 The Cori method and the Wallinga-Teunis method involve inferring the  
346 values of  $R_t$  that are most consistent with observed incidence data (for a review,  
347 see [29]). In the Cori method, typically this inference is carried out by assuming  
348 that  $R_t$  is constant over fixed time windows. Smoothing windows are used to avoid  
349 spurious fluctuations in estimates of  $R_t$ . These can occur if imperfect observation  
350 and reporting effects, rather than actual bursts in transmission, are the main source  
351 of noise in the data. Cross-validation and proper scoring rules can be used to avoid  
352 under- or oversmoothing  $R_t$  estimates [25].

353 An important concept, basic to both methods, is the intrinsic generation  
354 time also referred to as the infectiousness profile. The intrinsic generation interval is  
355 a theoretical quantity derived from the renewal equation of Lotka and Euler [37, 56].  
356 It describes the time distribution of potentially infectious contacts made by an index  
357 case, and is independent of population susceptibility [17]. In practice, the intrinsic  
358 generation interval is not observable, and it must be estimated carefully from  
359 observed serial intervals within contact tracing data [17, 45]. The serial interval is  
360 generally defined as the duration of time between onset of symptoms in an index case  
361 and in a secondary case [59]. In the early stages of an outbreak, accurate estimation  
362 should adjust for right truncation of observations, for changes over time in popula-  
363 tion susceptibility, and for interventions like case isolation, which may shorten the  
364 generation interval by limiting transmission events late in the course of infectious-

365 ness [2, 17, 45].

366 Both the Cori and Wallinga-Teunis methods are conceptually based on sep-  
367 arating the infectiousness of an infective into two components, total amount and  
368 timing. The timing is expressed by the generation time distribution while the total  
369 amount is expressed by  $R_t$ . The variation of (average) infectivity over time is as-  
370 cribed, at least in practical implementations of the methods, to changes in  $R_t$ , while  
371 the intrinsic generation time is assumed to remain fixed. This is a simplification that  
372 may lead to inaccurate estimation of  $R_t$ , since, in reality, the observed generation  
373 time distribution varies over time, both because of the epidemic dynamics [12, 55, 59],  
374 because of the epidemic affecting different subgroups of the population, with possi-  
375 bly different generation time distributions over time [35, 39], and, more importantly,  
376 because of interventions that affect the length or efficacy of the infectious period [2].  
377 An additional complication is that the “intrinsic” generation interval of the Cori and  
378 Wallinga-Teunis estimators includes potentially infectious contacts with both sus-  
379 ceptible and immune individuals, whereas only contacts with susceptible individuals  
380 cause new infections, and are observed in contact tracing [17, 45]. Even when using  
381 an accurately estimated, fixed generation time distribution, both  $R_t$  estimators are  
382 numerically sensitive to the specified mean and variance of the intrinsic generation  
383 interval [16].

### 384 3.2 Data used to estimate $R$

385 Fundamentally,  $R_t$  is a measure of transmission. Ideally, it would be estimated from  
386 data on the total number of incident infections (i.e. transmission events) occurring  
387 each day. But in practice, only a small fraction of infections are observed, and noti-  
388 fications do not occur until days or weeks after the moment of infection. Temporally  
389 accurate  $R_t$  estimation requires adjusting for lags to observation, which can be es-  
390 timated as the sum of the incubation period and delays from symptom onset to  
391 case observation [9, 16]. Delays not only shift observations into the future, they also  
392 blur infections incident on a particular date across many dates of observation. This  
393 blurring can be particularly problematic when working with long and variable delays  
394 (e.g. from infection to death), and when  $R_t$  is changing. Deconvolution [8, 23, 27, 41],  
395 or  $R_t$  estimation models that include forward delays [1] can be used to adjust lagged  
396 observations. Simpler approaches may be justifiable under some circumstances. If  
397 observation delays are relatively short and not highly variable, and if  $R_t$  is not rapidly  
398 changing, simply shifting unadjusted  $R_t$  estimates back in time by the mean delay  
399 can provide a reasonable approximation to the true value (see Challen *et al.*, in this  
400 volume, for an in-depth discussion [16]). The benefits and disadvantages of each  
401 approach are reviewed in [29]. Changes over time in case ascertainment can also  
402 bias  $R_t$  estimates, so ideally data should be drawn from structured surveillance (see,  
403 for example, the REACT study [33]) or adjusted for known changes in testing or  
404 reporting effort [33, 42].

405 In practice,  $R_t$  can be estimated from a time series of new symptom on-  
406 set reports, cases, hospitalisations or deaths. Choosing an appropriate data stream  
407 involves weighing representativeness, timeliness of reporting, consistency of ascertain-  
408 ment, and length of lag. For example, reported deaths may be reasonably unaffected  
409 by changes over time in ascertainment, but adjusting for long lags to observation  
410 can be challenging, and deaths may not be representative of overall transmission  
411 (e.g. if the epidemic shifts toward younger age groups) [40,50]. Extensions of exist-  
412 ing statistical models for  $R_t$  estimation could potentially integrate multiple kinds of  
413 data, by assuming that (e.g.) cases, hospitalisations and deaths, arise from a shared,  
414 latent infection process, with different delays [29]. A mechanistic model can also pull  
415 multiple data streams together by modelling the different processes underlying each  
416 data stream. Problems can arise if different data streams disagree on the progress  
417 of the pandemic. However, if the disagreement is caused by a shift in delays from  
418 events to reporting in different data streams, a mechanistic model can highlight these  
419 changes. Sometimes different data streams can be used for model validation.

420 All methods used to estimate  $R_t$  must decide on the length of the time  
421 window over which it is to be estimated. All data used to estimate  $R_t$  are noisy.  
422 The shorter the time window used for estimation, the higher will be the noise-to-  
423 signal ratio and, therefore, the uncertainty in the estimate of  $R_t$ . In contrast, longer  
424 time windows will produce estimates with lower uncertainty, but sudden changes in  
425 transmission may not be detected if the time window is too long.

## 426 4 Summary: Cautions and Recommendations

427 During the early phase of the epidemic:

- 428 •  $R_0$  estimates in the early phase may not be representative for the population  
429 as a whole if the group of initial transmitters is atypical.
- 430 •  $R_0$  may be incorrectly estimated in the early phase if infected but asymptomatic  
431 individuals are not counted or recognised, and their epidemiologically relevant  
432 behaviour differs from that of symptomatic individuals.

433 When the epidemic is established in the population:

- 434 •  $R_t$  can differ for different population groups, and the value of  $R_t$  is dominated by  
435 the group in which most transmission occurs. To improve targeted containment  
436 measures, where possible additional information should be reported alongside  
437 case data, such as demographic, socio-economic and occupational information.
- 438 • The estimated value of  $R_t$  and its associated uncertainty depend on the data  
439 stream(s) used and the time window over which  $R_t$  was estimated, and these

440 should be reported alongside the estimates. This will make it possible to draw  
441 more robust conclusions when considering results from different models.

- 442 • Model components that are likely to change over the time course of the epi-  
443 demic (e.g. the generation time distribution) should be updated regularly, and  
444 sensitivity to changing assumptions should be kept under consideration.

445 When the ongoing epidemic is fragmented:

- 446 •  $R_t$  estimates from local outbreaks, if they can be contained, cannot inform on  
447 the progress of the epidemic and efficacy of interventions at the national level.  
448 They may inform local interventions. Other descriptors should be considered  
449 to assess the progress of the epidemic, such as the number of new cases per  
450 capita per day in a defined area, the number of hospitalisations and the spare  
451 hospital and intensive care capacity.
- 452 • Imported cases that are effectively quarantined should not be counted towards  
453  $R_t$  estimates as they do not contribute to the local transmission potential in  
454 the community.

455 Vaccination and herd immunity:

- 456 • If the available vaccine supply is limited, optimal vaccination strategies should  
457 be designed that take into account population structure and the transmission  
458 potential within different groups and other public health priorities, e.g. pro-  
459 tection of the vulnerable groups.

460 In conclusion, estimated  $R$  values do not exactly correspond to the theoretically de-  
461 fined quantities. In statistical terms, model uncertainty, sampling variability, and  
462 data accuracy affect the estimates. Nevertheless,  $R_0$  and  $R_t$  are useful quantities to  
463 assess the potential and progress of an epidemic. Their usefulness for decision mak-  
464 ing varies depending on the phase of the epidemic (early, established, fragmented).  
465 Clearly defining the context, the data streams and the statistical methods used to  
466 estimate  $R$  can improve its value for the management of an epidemic.

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