

1    **Robust Estimation of Snare Prevalence Within a Tropical Forest Context**  
2                                    **Using N-Mixture Models.**

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13

14 **Abstract**

15 Hunting with snares is indiscriminate and wasteful, and this practice is currently one of the gravest  
16 threats to terrestrial vertebrates in the tropics. However, as snares are difficult to detect and often  
17 dispersed widely across large, inaccessible areas it is problematic to reliably estimate their prevalence  
18 and no standard survey methods exist. Conservation managers need reliable, timely, information on  
19 the spatio-temporal patterns of hunting and on responses to interventions, and we present an  
20 innovative sampling and analysis framework that allows for the rigorous estimation of snare  
21 detectability and ‘abundance’, but which can be feasibly implemented in challenging field contexts.  
22 This new approach was used to undertake a large-scale systematic snare survey in Keo Seima  
23 Wildlife Sanctuary, in Eastern Cambodia, and the resulting data were analysed using a novel  
24 application of N-mixture models. A range of environmental and management factors were examined  
25 as potential determinants of snare abundance and detectability, and proximity to the Vietnamese  
26 border was shown to be overwhelmingly the most influential factor. Snares were more common in the  
27 wet season rather than the dry season, and the detection probability of snares was shown to be low (~  
28 0.33), as predicted. No clear relationships between snaring levels, anti-poaching patrol effort and  
29 ungulates densities were evident from these data. There was clear evidence that certain factors, such  
30 as the percentage of dense forest cover, will exert confounding effects on both detectability and  
31 abundance, highlighting the critical need to take account of the imperfect detection when designing  
32 threat monitoring systems.

33 **Key Words**

34 snare; hunting; n-mixture models; detection probability; tropical forests; threat monitoring

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## 36 **1. Introduction**

37 Illegal hunting, be it for local subsistence or to supply ever-expanding markets with meat, pets, trophies  
38 and other body parts, arguably constitutes the greatest current threat facing wild vertebrates in tropical  
39 Asia and Africa (Corlett 2007; Fa & Brown 2009; Harrison et al. 2016). Unsustainable hunting can have  
40 dire consequences not just in terms of causing species extirpations and degrading the ecological integrity  
41 of forest systems, but also through its impact on the livelihoods of the rural, often marginalised, people  
42 who depend on these resources (Milner-Gulland & Bennett 2003; Fa et al. 2016).

43 Traditional approaches to the monitoring poaching and other forms of illegal resource use (i.e. interview-  
44 based techniques, self-reporting, direct observation) all have methodological challenges associated with  
45 them (Gavin et al. 2010). This is largely due to the fact that offenders typically have strong incentives to  
46 conceal the true nature of their activities from investigators, potentially leading to severe and  
47 unquantifiable bias in estimates of the prevalence of illegal resource-use (Keane et al. 2008; Gavin et al.  
48 2010). With the global roll-out of standardised law enforcement monitoring systems such as SMART,  
49 there has been a growing interest in threat data collected during routine patrols (i.e. encounters of  
50 infractions; e.g. Jachmann 2008; Linkie et al. 2015), and the use of such cheap and readily available data  
51 will undoubtedly continue to increase. However, as essentially a by-product of efforts to deter illegal  
52 activities, these data typically also contain severe biases which can limit their utility for threat monitoring  
53 purposes (Gavin et al. 2010; Keane et al. 2011).

54 Any attempt to estimate the prevalence of a given threat can be affected by the same two sources of bias  
55 which affect all ecological surveys, imperfect detection and unrepresentative spatial sampling (Williams  
56 et al. 2002). The importance of considering these potential biases when designing ecological monitoring  
57 programs has been repeatedly highlighted (Yoccoz et al. 2001; Legg & Nagy 2006; Nichols & Williams  
58 2006) but these issues are equally applicable to the monitoring of threats such as hunting. Employing a  
59 probabilistic sampling strategy and investing in sufficient survey effort can ensure representativeness  
60 (Brashares & Sam 2005), but accounting for detection error can be more challenging. The problem of  
61 imperfect detection is of particular relevance to illegal hunting, not only because it precludes reliable

62 monitoring of this threat, but also because a key factor in successful poaching deterrence is a high rate of  
63 detection (Leader-Williams & Milner-Gulland 1993; Hilborn et al. 2006). And yet, to our knowledge,  
64 there are no published studies which attempt to estimate the extent or impact of illegal hunting using  
65 systematic surveys which account for imperfect detection.

66 The development of flexible hierarchical models has greatly improved researchers' ability to  
67 simultaneously account for variation which is related to spatial or temporal variation in an underlying  
68 ecological process of interest (i.e. occurrence or abundance) and variation which is due to the imperfect  
69 observation of this process (i.e. detectability Royle & Dorazio 2008; Kéry & Royle 2016). One class of  
70 hierarchical models are the multinomial and binomial mixture models of Royle (2004 a,b), which to date  
71 have been most frequently used in the analysis of avian point count data, although they have also been  
72 employed in the study of mammal and amphibian populations (Mazerolle et al. 2007; Zellweger-Fischer  
73 et al. 2011). A natural extension of these methods is to adapt them for modelling observations of hunting  
74 rather than of wildlife.

75 We present a case study in which binomial mixture models, or 'N' mixture models, are used to generate a  
76 robust estimate of snaring prevalence in a protected area in Eastern Cambodia. As elsewhere in the  
77 tropics, wire snares are a common method of hunting in this region, as the equipment involved is  
78 affordable and easily accessible, and the technique is effective for a wide range of vertebrate species  
79 (Noss 1998; Becker et al. 2013). This form of hunting is particularly detrimental because in practice it is  
80 often indiscriminate and wasteful (Lindsey et al. 2011; Gray et al. 2017), and the use of snares is  
81 therefore illegal in Cambodia. However, the covert nature of this activity means that it is extremely  
82 difficult to detect perpetrators or snares, and consequently the enforcement of snaring prohibitions is  
83 challenging (Noss, 1998). Although some surveys have been undertaken in Africa (i.e. Wato et al. 2006;  
84 Lindsey et al. 2011; Becker et al. 2013) none of them address the detection issue, and almost no studies  
85 have been carried out in Southeast Asia (but see Linkie et al. 2015). This is despite the fact that hunting  
86 with snares represents one of the gravest threats to terrestrial biodiversity in the region (Gray et al. 2017).  
87 Without accurate measurement of such threats, managers cannot easily evaluate the success of

88 conservation actions designed to reduce snaring levels, or design more effective interventions as a result  
89 (Hockings et al. 2000).

90 The aim of this study was to develop an approach which could reliably estimate the abundance and  
91 detectability of snares, but that could be implemented within a typically challenging tropical forest  
92 context. Our objectives were both methodological and relevant to management, and related both to the  
93 field component and the subsequent modelling process:

94 *Objective 1.* Develop an appropriate sampling design for a snare survey to produce data suitable for  
95 analysis within a hierarchical modelling framework. *Objective 2.* Analyse the resultant snare survey data  
96 using N-mixture models to generate a detectability-corrected spatially explicit index of snare abundance.  
97 *Objective 3.* Within this modelling framework, investigate *a priori* hypothesised relationships between a  
98 range of potential covariates and both snare detectability and snare abundance.

## 99 **2. Methods**

### 100 *2.1 Methodological Framework*

101 Any application of N-mixture models requires both spatial and temporal replication within the data  
102 (Royle 2004a, 2004b; Kéry et al. 2005), hence a sampling design was required which incorporated both  
103 multiple sites and repeated surveys of each site. In practical terms, although relatively numerous, snares  
104 are extremely difficult to detect (O’Kelly et al. 2017). They also tend to be aggregated in space at one  
105 scale (i.e. where one hunter operates) whilst also dispersed across a large survey area (i.e. the entirety of  
106 the protected area). Therefore, the sampling design necessarily involved a balance between maximising  
107 the efficiency of data collection and adhering to best practice in terms of scientific rigour.

108 N-mixture models are extensions of the Poisson generalized linear model (GLM) or generalized linear  
109 mixed model (GLMM), but they include an additional stochastic component that explicitly models the  
110 observation process (Kéry & Royle 2010, 2016). These models can produce estimates of abundance  
111 without the need for the identification of individuals, and they are particularly appropriate for scenarios

112 where data are relatively sparse (Royle 2004a, 2004b). These models are also useful for investigating  
113 how both the abundance and detection processes vary as a function of both ecological and management  
114 factors (i.e. Chandler et al. 2009; Chandler & King 2011).

115 Our modelling approach incorporated two stages, the first of which examined covariates for which we had  
116 some clear *a priori* hypothesis regarding their relationship to abundance and/or detectability. The second  
117 phase involved including additional covariates in order to explore the relationship between threats (i.e.  
118 snaring rates), interventions (i.e. patrol effort) and impacts (i.e. wildlife densities). Whilst the  
119 relationships and potential causal linkages of the second stage are of fundamental interest to conservation  
120 managers, they are difficult to predict *a priori* or to interpret with any certainty.

## 121 *2.2 Study Site*

122 The Keo Seima Wildlife Sanctuary (KSWS) covers a 292,690ha mosaic of evergreen, semi-evergreen  
123 forest and deciduous forest in eastern Cambodia. Biodiversity values within KSWS are high, as it holds  
124 globally or regionally significant populations of elephants and wild cattle, and multiple species of  
125 primates, carnivores and large birds (Evans et al. 2012; O’Kelly et al. 2012).

126 The 20,000 people living near or within KSWS comprise both indigenous ethnic minorities and ethnic  
127 Khmer, the latter having arrived during a more recent wave of in-migration. Agriculture is the dominant  
128 livelihood activity but residents are also heavily forest dependent and a critical source of income for many  
129 families is tapping of liquid resin from *Dipterocarpus* trees, which takes place widely throughout the  
130 reserve (Evans et al. 2012). The most significant threat to key wildlife species in KSWS is over-hunting  
131 and several large mammal species have been extirpated from the area (O’Kelly et al. 2012). Populations  
132 of many other taxa have been drastically reduced by hunting with guns and, more commonly, snares, both  
133 of which are prohibited.

## 134 *2.3 Sampling Design and Field Protocols*

135 Sampling took place across the 187,983 ha core area of KSWS in 37 clusters of 12 x 1km<sup>2</sup> “sites”.  
136 Clustered sites formed a circuit around a set of permanent line transects used for long-term wildlife  
137 monitoring and positioned using a systematic design with a random starting point (O’Kelly et al. 2012).  
138 The cluster design maximised sampling efficiency but at the cost of inducing potential non-independence  
139 of sites within a cluster.

140 However, each cluster of sites was assumed to be spatially independent with respect to both hunter and  
141 prey movement during the study period. The distance between clusters was c.7km which is greater than  
142 the ranging distances of any of the target species and likely to be much further than the distances typically  
143 covered by hunters in this terrain (patches of <1 km<sup>2</sup>, HJOK pers obs).

144 Between February 2011 and February 2012, all 37 clusters were sampled over a two to four-day period,  
145 which ensured that sites were closed to changes in snare abundance over the course of the study. The  
146 majority of clusters (28) were surveyed by two field teams, over the same time period but working  
147 independently of one another. Nine clusters were surveyed by only one team due to logistical constraints.  
148 Teams walked a minimum of 2km per 1km<sup>2</sup> site, choosing routes likely to maximise the detection of  
149 snares, whilst also attempting to achieve maximum spatial coverage of each site.

150 Two main types of snare are common within KSWS; single snares (usually medium or large-sized and  
151 constructed using thick wire rope), and snare lines consisting of multiple smaller snares (typically  
152 constructed from much thinner wire, as is typically used for brake cables) set along a low drift fence  
153 constructed from bamboo and brushwood. The actual number of snares, and whether they are set, is  
154 clearly relevant with respect to mortality risk but during this study an observation corresponded to a snare  
155 “incident” regardless of the type or number of snares concerned. In terms of detectability, only the first  
156 snare in a drift line is important, as all others in the line will have a detection probability of close to 1.

157 The locations of all snare incidents encountered was recorded using GPS units, together with the number  
158 of snare(s), estimated age of snare(s), habitat type and evidence of any captures (i.e. live animals,

159 carcasses, bones etc.). Cables and wires were removed from all snares, and anchor poles were cut, thus  
160 preventing future use of the structure.

### 161 **3. Data Analysis**

#### 162 *3.1 Binomial Mixture Models*

163 The simplest of N-mixture models assumes that there are no changes in abundance over the survey  
164 period, in which case repeated counts (corresponding to visits by multiple survey teams in this case)  
165 within sample location  $i$  are treated as independent realizations of a binomial random variable with  
166 parameters  $N_i$  (local abundance) and  $p_i$  (detection probability). It is further assumed that  $N_i$  comes from  
167 some common distribution specified by parameters to be estimated from the data. The structure of these  
168 models is described in detail in Royle (2004a, b) and Kéry et al. (2005).

169 N-mixture models, like other classes of hierarchical model, can accommodate a range of covariates  
170 hypothesised to influence both abundance and detection probability. Site-level covariates are  
171 related to conditions which remain constant across surveys (e.g. forest type). Observation or  
172 survey-level covariates are related to individual surveys and thus may differ or remain the same  
173 across surveys (e.g. precipitation). The effects of covariates on abundance and detectability are  
174 modeled linearly in a GLM fashion via a log-link function. All models in this analysis were fitted  
175 using the package “unmarked” (Fiske & Chandler 2011) in R version 2.14.0 (R Core Team 2012).  
176 The fitting function “pcount” within the unmarked package fits the N-mixture model of Royle  
177 (2004).

178

#### 179 *3.2 Modelling Process*

180 A wide range of factors are likely to influence the abundance, distribution, and detectability of snares. A  
181 full list of the potential covariates considered is given in Table 1A (supporting material). Correlations  
182 between covariates were examined to eliminate redundancy and all covariates were standardized. Route  
183 length was log-transformed and all other covariates were transformed into standard normal deviates. For  
8



184 this analysis, we specified a Poisson mixture distribution to model latent snare abundance. We used  
185 parametric bootstrapping to evaluate the goodness-of-fit of the final set of selected models using chi-  
186 square and Freeman Tukey fit statistics.

187 Given the complexity of the study system, we focused on a limited set of candidate models with the  
188 intension of avoiding over-parameterisation (Johnson & Omland 2004). We used a multi-step process to  
189 investigate *a priori* hypotheses on factors affecting abundance and detectability of snares, and to  
190 investigate additional relationships. For model selection, we used a ranking system based on Akaike's  
191 Information Criterion (AIC) and  $\Delta AIC$  (assuming models with  $\Delta AIC < 2$  are broadly equivalent in terms  
192 of fit).

193 In step one, we modelled snare abundance as a function of site-level covariates (% dense forest cover,  
194 terrain ruggedness, season, distance to village, distance to patrol station, distance to reserve boundary,  
195 distance to international border). Quadratic effects were included where non-linearity was expected (i.e.  
196 as a function of distance to village and terrain ruggedness) as was an offset using log-transformed effort  
197 (km walked) per site. The best fitting models were selected to take forward to the next step.

198 In step two, we modelled covariates hypothesised to affect detection probability. These included the site-  
199 level covariate of proportion of dense forest cover, which remained constant across visits, and the survey-  
200 level covariates of relative climb and survey effort which were specific to a visit. Top-ranked models  
201 selected from step one were extended to include all combinations of these covariates.

202 In step three, we examined models containing covariates that theoretically may affect abundance but for  
203 which the functional relationship between variables is likely to be of a more complex nature. The  
204 covariates considered during this phase included ungulate densities (distance sampling-derived density  
205 estimates from line transects within each cluster) and various of measures of anti-poaching patrol effort  
206 (km patrolled on foot and motorbike). Finally, we used the top-ranking models to create spatially explicit  
207 predictions of detectability-corrected snare abundance across the entire core area, based on known  
208 covariate values.

210 *4.1 Snare Encounters and model selection*

211 During the 2,200km of search effort across the 440km<sup>2</sup> survey area, 140 snaring incidents were  
212 encountered (64 single snares and 76 snare lines) (Figure 1). The sites with one or more encounters  
213 (ranging between 1-6 per site) were dispersed across 18 of the 37 clusters. Over 1,300 wire/cables were  
214 removed by survey teams and all snare lines encountered were destroyed.

215 For the abundance component of the modelling process, the top four models ( $\Delta AIC < 2$ ) included dense  
216 forest, distance to reserve boundary, distance to international border, distance to village, and season (  
217 Table 2A supporting material). These models were taken forward to step two of the process.

218 When all combinations of these detection-related covariates were added to the models selected above,  
219 AIC ranking resulted in a further four top models (Table 2A supporting material). All of these models  
220 were taken forward to the more exploratory stage of the analysis described below. Goodness-of-fit  
221 statistics are provided in Table 3A (supporting material).

222 In the final phase of the modelling process the inclusion of covariates related to patrol effort generally had  
223 a negative effect on snare abundance but only minimally improved model fit (Table 4A supporting  
224 material) The inclusion of covariates relating to animal density generally did not improve model fit as  
225 measured by AIC (Table 4A supporting material). Therefore, the top-ranking model from step two was  
226 used to create spatial prediction of snare abundance based upon the known range of influential covariates  
227 (see section 4.3).

228 *4.2 Estimates of Detectability and Abundance*

229 When applied to avian point count data, for which they were originally developed, N-mixture models  
230 produce estimates of the average abundance of birds per sample location. In this study, given the use of  
231 survey effort in km as an abundance offset, abundance can be interpreted as the expected number of snare  
232 incidents per 1km surveyed. Since the width of the survey routes was not fixed, the effective area sampled

233 is unknown and expected density of snares per site cannot be calculated. In addition, because counts  
234 corresponded to snare incidents rather than actual numbers of snares, the resultant measure can be most  
235 appropriately viewed as an index of snare abundance.

236 None of the covariates tested at step three of the modelling process improved model fit significantly and  
237 hence we proceeded with the top-ranked models from step two (Table 1). For each of these highest-  
238 ranking models, back-transformed estimates of expected probability of detection and indices of  
239 abundance when all the relevant covariates are fixed at their mean are given in Table 5A. Abundance  
240 estimates for models containing covariates differ substantially from the null model, which treats  
241 abundance and detectability as constant. Estimates of detectability remain relatively consistent across  
242 models, at either around 0.28 or 0.36, indicating that on average only one snare incident is detected for  
243 every three that could potentially be detected.

#### 244 *4.3 Predicted Snare Distribution*

245 Spatially explicit predictions of detectability-corrected snare abundance across the entire core area are  
246 mapped in Figure 2, based on the best model from step 2 (Table 1). Snaring is heavily concentrated in the  
247 Southern sector of the site, close to the Vietnamese border and around villages and patrol stations. North  
248 of the main road, levels of snaring drop off rapidly and a large proportion of the Northern sector of the  
249 reserve appears to be virtually devoid of snares. It is worth noting that the Southern sector of the reserve  
250 is also the area with the highest proportion of dense evergreen forest whereas the Northern sector is  
251 dominated by open dry forest (Figure 1).

#### 252 *4.4 Covariate Effects on Abundance and Detectability*

253 The inclusion of covariates within models allows us to quantify relationships between abundance and key  
254 environmental gradients. We can examine predictions of abundance for any of the covariates individually,  
255 by specifying a range for each of the covariates of interest whilst fixing all other covariates at their mean  
256 value.

257 Using this approach, predicted estimates of snare abundance in the dry season are approximately one third  
258 lower than equivalent estimates for the wet season. In terms of forest type, a typical location has just  
259 under 50% dense forest cover, and snare abundance is extremely low in sites with below average cover.  
260 Above this average level, predicted abundance increases rapidly as the proportion of dense forest cover  
261 increases, and predictions for sites with full cover are over six times higher than for an average site. With  
262 respect to proximity to villages, predictions of snare abundance initially decrease as distance to village  
263 increases, up to approximately seven kilometres, after which they begin to increase with greater distances  
264 from villages. At 13 kilometres from a village, snare abundance is predicted to be three times higher than  
265 the average, but abundance is at its highest around the outskirts of villages, where it is predicted to be four  
266 times higher than average. Snare abundance decreases both with distance to the reserve boundary and  
267 with distance to the international border. However, whereas predicted snare abundance within one  
268 kilometre of the reserve boundary is over just 25% higher than the average, predicted abundance within  
269 one kilometre of the international boundary is greater than the average by two orders of magnitude,  
270 indicating the stark difference between the strength of these effects. When terrain ruggedness is included  
271 in models, predictions of snare abundance increase as terrain ruggedness increases, but differ from the  
272 average by less than 10%. Surprisingly, snare abundance appears to decrease with distance to patrol  
273 station. However, this effect is relatively weak, with predicted abundance at one kilometre from a station  
274 just 20% higher than the average, whilst predictions at the maximum distance of 26 kilometres from a  
275 station are 35% lower than the average.

276 In the more exploratory models, predicted snare abundance for a site with no patrol visits is less than 5%  
277 higher than predicted abundance for a site with the average number of patrol visits (3.5). There was also a  
278 negative relationship between wild cattle and wild pig density and snare abundance, whereas the  
279 relationship between muntjac density and snare abundance was positive.

280 The same approach can be used to explore how both site level and survey level covariates affect  
281 detectability. Detectability decreased with increasingly dense forest cover, such that predicted  
282 detectability in sites with 10% forest cover is seven times higher than a site with 100% forest cover. A

283 steeper relative slope on the route surveyed also reduced detectability such that predictions of  
284 detectability on the flattest routes are up to 10 times higher than for the steepest routes surveyed. Finally,  
285 route length had a positive relationship with detectability; for example, predictions of detectability for  
286 routes of three kilometres were 20% higher than for routes of two kilometres.

## 287 **5. Discussion**

### 288 *5.1 Determinants of Snare Detectability and Abundance*

289 The relationships between snare abundance and dense forest cover, terrain ruggedness, distance to  
290 boundary, and distance to international border corresponded to *a priori* predictions, as did the  
291 relationships between detectability and dense forest cover and relative climb of survey routes.

292 The importance of dense forest cover in influencing snare placement is unsurprising, given that hunters  
293 rely on this type of forest to construct and conceal snares, and that wildlife populations also depend  
294 heavily on the availability of this habitat type. However, the fact that dense forest negatively affects the  
295 detectability of snares, whilst simultaneously exerting a positive effect on snare abundance, demonstrates  
296 how crucial it is to account for imperfect detection in these types of surveys in order to avoid biased  
297 results.

298 Proximity to population centres and markets are a major determinant of hunting occurrence and in this  
299 case we see the overwhelming influence of the location of the Cambodian/Vietnamese border on snare  
300 abundance. This can be attributed to the extremely high demand on the Vietnamese side (Shairp et al.  
301 2016; Sandalj et al. 2016), which is driving an influx of hunters into KSWs from across the border (WCS  
302 Cambodia Program, unpublished data).

303 The relationship between snare abundance and distance to village illustrates how multiple processes can  
304 influence snare distribution at different scales. Snaring levels are high in the southern part of the reserve,  
305 close to the Vietnamese border, and also close to the larger settlements located in the southeastern and  
306 southwestern corners of the reserve. However, several other snaring patterns are also evident. Reserve

307 residents commonly set snares around the outskirts of their fields (to combat crop raiding), in the  
308 immediate vicinity of the village. When residents go into the forest specifically to hunt, the distance they  
309 travel is presumably limited by several factors including their mode of transport (i.e. on foot or by  
310 motorbike) and their food and/or fuel supplies. Nevertheless, some residents travel considerable distances  
311 from their villages in order to visit their resin trees, and in these instances, they may spend several days or  
312 even weeks at temporary “resin camps” and they will set snares during this time (WCS Cambodia  
313 Program, unpublished data). This gives rise to a complex, non-linear relationship between snare  
314 abundance and distance to village.

315 Prior to this study, conflicting hypotheses existed regarding the seasonality of snaring within this  
316 landscape. The predominant theory was that snaring levels increased in the dry season when access to the  
317 reserve is easier and wildlife populations tend to be aggregated around water and food sources. However,  
318 other local reports had suggested that hunters focused their efforts during the wet season, to take  
319 advantage of the greater cover afforded by dense foliage and damp ground, and possibly also a reduction  
320 in anti-poaching patrol effort, as a well as a gap in the local agricultural calendar. The results of this  
321 survey indicate that hunting levels are appreciably higher during the wet season.

322 The apparent negative relationship between snare abundance and distance to patrol stations may seem  
323 counter-intuitive but it is important to note that patrol stations within the KSWS have been placed  
324 strategically, in locations where threat levels are known to be particularly acute and/or in locations known  
325 to be particularly important for key wildlife species. Indeed, areas of perceived high animal density are  
326 precisely the areas likely to be targeted both by hunters *and* by management and enforcement agencies.  
327 Levels of hunting may remain proportionally higher in these areas despite the presence of a station  
328 (although presumably they would be lower than pre-station levels). Alternatively, the presence of a station  
329 may afford localised protection which allows prey populations to recover, only for them to be  
330 subsequently targeted by hunters who are aware of this recovery.

331 Various types (i.e. vehicle, motorbike and foot) and combinations of patrol effort were tested as  
332 potentially useful covariates, but these data provided little support for patrol effort as an important

333 predictor of snare abundance. The complex relationship between enforcement effort and illegal activities  
334 has been highlighted within the literature (Keane et al. 2008, 2011) and may explain in part the apparent  
335 lack of any obvious deterrent effect. However, it seems likely that these results may also be related to the  
336 spatial and temporal scale of this study. Due to limited patrol coverage by law enforcement teams during  
337 the study period, a large proportion of survey sites had no patrol effort associated with them. This was  
338 particularly pronounced in the case of foot patrols, which were only recorded in less than 10% of survey  
339 sites, despite being the most efficient type of patrol to locate snares (WCS Cambodia Program,  
340 unpublished data). Furthermore, temporal lags of varying lengths may occur between patrols and any  
341 subsequent deterrent effect, and the duration of any such effect is unknown. The spatial scale at which  
342 any deterrent effect will operate at is also unknown and is likely to be dependent on a multitude of factors,  
343 such as patrol type and habitat characteristics (Keane et al. 2011). In this study the unit of analysis was a  
344 one km square site and patrol effort was calculated as the number of patrols deployed within that site over  
345 a one year period preceding the survey. This seemed a realistic scale at which a deterrent effect might be  
346 evident, but a wide range of alternatives spatial and temporal specifications could have been chosen.

347 The relationship between snaring levels and wildlife population densities is of fundamental interest to  
348 conservation managers but care must be taken when attempting to demonstrate causal linkages between  
349 the two. Relationships are likely to be spatially and temporally scale dependant, as above, and may be  
350 obscured by confounding variables. For example, an area with apparently low levels of snaring and low  
351 wildlife densities may have naturally fewer animals due to some unmeasured habitat characteristics, thus  
352 rendering it unappealing to prospective hunters. However, this same scenario could be as a result of  
353 overhunting in area which previously had higher wildlife densities, which were then depleted through  
354 hunting, eventually causing hunters to shift their activities to other more productive areas. Further  
355 complexity can arise when wildlife abundance and hunting levels are determined by the same factors. In  
356 the KSWS both wildlife densities and hunting levels are high in the southern section of the reserve, which  
357 is the area closest to the international border and also the area with the greatest proportion of dense forest.  
358 Proximity to the border may directly influence snaring levels but it does not directly influence wildlife

359 abundance, whereas the presence of dense forest is likely to be a direct determinant of snare occurrence  
360 *and* wildlife occurrence.

361 Although the modelling results yield little support for individual species densities as significant predictors  
362 of snare abundance, the direction of effects within models is of interest and appears to corroborate other  
363 sources of information, including biological monitoring data and field observations. The positive  
364 relationship between snare abundance and red muntjac density does suggest that hunters purposefully set  
365 snares in areas of higher muntjac abundance. This species is known to be a preferred prey choice for  
366 hunters and likely experiences high hunting pressure (Drury 2005; O’Kelly et al. 2012). Despite this,  
367 muntjac remain moderately abundant in comparison to other ungulate species, there is no evidence of a  
368 decline apparent from biological monitoring data and they persist widely throughout the reserve (O’Kelly  
369 et al. 2012). When taken together, the temporal trend data for this species and the spatial relationships  
370 inferred from the snare survey results appear to indicate a relative resilience to hunting pressure, a  
371 supposition which has been suggested in other studies (Steinmetz et al. 2010).

372 Including wild pig and cattle densities as covariates within models did not improve model fit, but it did  
373 suggest a negative relationship between these species’ densities and snare abundance. Wild pig is one of  
374 the commonest species to appear in hunting records (FA/WCS, unpublished data) and biological  
375 monitoring data suggest that, whilst still relatively healthy, this population is undergoing a decline  
376 (O’Kelly et al. 2012). The wild cattle population within KSWS is small, declining, and potentially  
377 particularly vulnerable to the threat of hunting (O’Kelly et al. 2012). Although it is likely that snaring is  
378 having a negative impact on wild pig and cattle populations, the evidence provided by this study is  
379 inconclusive and further work is needed to establish to what extent snaring is contributing to these  
380 declines.

## 381 *5.2 Methodological Implications*

382 Previous studies which utilise snare encounter data routinely collected by law enforcement teams (e.g.  
383 Becker et al. 2013; Linkie et al. 2013) are limited by the fact that law enforcement patrols are reactive and



384 strongly non-random in nature, meaning that such data are inherently biased (Keane et al. 2008). Studies  
385 which focus on snares but ignore the critical issue of detectability (e.g. Wato et al. 2006; Lindsey et al.  
386 2011; Becker et al. 2013) risk yielding unreliable results because they rely on biased estimators of  
387 occurrence or abundance (MacKenzie et al. 2002). Our approach addresses these issues and generates  
388 robust estimates whilst also remaining feasible to implement in difficult field conditions.

389 The modelling process described here allows us to disentangle potentially confounding effects on both  
390 detectability and abundance, such as forest cover in this study, that could otherwise lead to misleading  
391 results. It also helps us to better understand the spatial dynamics and causal mechanisms underlying  
392 snaring, by offering a flexible framework within which to model the often complex and non-linear  
393 relationships between detectability and occurrence and a range of natural and anthropogenic covariates.  
394 Within this study the effect of distance to village on snare abundance provides a good example of such a  
395 relationship.

396 Despite the potential of the approach described here, there are still some methodological issues which  
397 require further investigation. The level of temporal replication in this study was minimal, primarily due to  
398 logistical constraints. Increasing the number of site visits (or using more simultaneous observers) in future  
399 surveys might allow for improved modelling of detection probability. In addition, our sampling design  
400 was based on clusters of sites, again due to logistical constraints, and this may have resulted in some  
401 spatial non-independence. The use of covariates helps to address this issue and where models fit well as  
402 indicated by GoF tests, as in this study, the dependence structure may not be a major concern. Future  
403 studies should also consider explicitly modelling how the characteristics of an individual snare incident  
404 might affect detection probability (i.e. single snares, short snare lines, long snare lines; type of wire/cable  
405 used; age of snares; whether snares or set or not etc.).

### 406 *5.3 Management Implications*

407 This approach allows us to produce detectability-corrected predictive maps of snare abundance and also  
408 provides a means of evaluating how changes in key covariates might potentially affect hunting prevalence  
409 and detection probability. Both of these aspects offer considerable management utility as they can be used

410 to guide current and future interventions in a more targeted way, in the expectation of improving  
411 management effectiveness.

412 A survey of the type described here could be repeated periodically to estimate temporal change in snaring  
413 patterns and this would allow managers to monitor the actual impact of enforcement interventions, and to  
414 assess the relative success of different anti-snaring strategies. However, it is acknowledged that this type  
415 of survey entails a significant investment of resources, which may have to be diverted away from already  
416 severely overstretched law enforcement regimes.

417 These law enforcement regimes may already involve the collection of snare encounter data as part of  
418 routine patrols, particularly as standardised systems for law enforcement monitoring such as SMART are  
419 rapidly becoming the global standard (SMART Partnership 2015). The appeal of using increasingly  
420 ubiquitous SMART data to monitor threats such as hunting is obvious. However, the analysis and  
421 interpretation of such data is fraught with difficulties (Gavin et al. 2010; Keane et al. 2011), and there is  
422 an urgent need to complement it with a better understanding of the underlying biases. The type of  
423 independent threat assessment undertaken in this study is crucial to this enterprise, as it can provide a  
424 means of validating and calibrating SMART data-derived measures.

## 425 **6. Conclusion**

426 In KSWS, as elsewhere, managers require reliable, real-time information on spatio-temporal patterns of  
427 hunting in order to implement effective anti-poaching measures. Disentangling the multiple processes  
428 which underlie apparent patterns of snare abundance presents significant methodological challenges and  
429 implementing data collection activities on the ground entails a raft of practical considerations. In this  
430 study, we have presented an integrated sampling methodology and analysis framework which offers  
431 considerable potential for more reliable estimation of the extent and distribution of illegal resource use,  
432 despite the often cryptic and highly variable nature of these activities. Although resources for assessing  
433 the status and trends in threats such as hunting are typically limited, often a variety of sources of relevant  
434 data may exist (including high quality data from biological monitoring and basic law enforcement

435 monitoring data). Multiple data sources can facilitate triangulation (Gavin et al. 2010) and having some  
436 more robust measures of threat can both contribute to, and validate, this process of triangulation. We  
437 would contend, therefore, that periodic independent threat assessments of this nature represent a  
438 necessary and worthwhile investment of scarce conservation resources, particularly if carried out  
439 relatively infrequently.

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