

A Planar CMOS Field-Emission Vacuum Magnetic Sensor

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Abstract—We have fabricated a CMOS vacuum magnetic sensor that exploits the deflection of an electron beam produced by field emission by a perpendicular magnetic field. The device is planar and fabricated by conventional lithography and etching processes. An extremely high magnetic field sensitivity of $4 \times 10^3\%/T$ is reported.

Index Terms—CMOS, field emission, magnetic sensing.

I. INTRODUCTION

THE FIELD OF magnetic sensing is dominated by Hall-effect sensors, which have the advantages of ease of fabrication and compatibility with silicon-based microelectronics. For field strengths between 0.1 mT and 1 T, they are convenient and cheap. However, they are highly sensitive to temperature and suffer from offset voltages that are indistinguishable from applied magnetic fields. This limits their sensitivity to low-frequency or static magnetic fields, as does their susceptibility to $1/f$ noise. Notwithstanding recent works on Hall-effect sensors with integrated on-chip control circuitry and current spinning technology to reduce noise and offset [1], [2], their long-term stability of sensitivity and offset remain problematic, and mechanical stress affects the zero-field offset through the piezoresistive effect. Competing technologies such as anisotropic magnetoresistance, colossal magnetoresistance, and superconducting quantum interference devices (SQUIDS) offer extremes of sensitivity, but suffer from expense and complexity of manufacturing and operation, and are therefore used in applications in which high sensitivity is paramount. Fluxgate magnetometers, which offer resolutions down to fractions of a picotesla, suffer from high power consumption and cost, along with large size. Despite recent impressive progress on miniaturization of such sensors [3], a gap in the market exists for a magnetic sensor which has high sensitivity and broad measurement range and is small, cheap to manufacture, and compatible with silicon VLSI. The vacuum magnetic sensor (VMS) is a promising solution.

In the VMS, a sharp conducting tip is placed close to a gate electrode that produces an electron beam by field emission. This beam propagates through a vacuum and is detected using a split

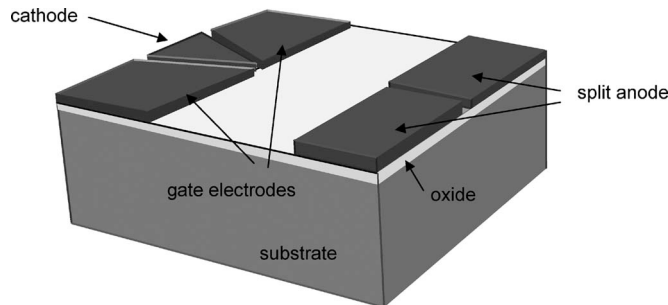


Fig. 1. Schematic layout of the planar VMS device.

anode. Any difference in the current received by each half of the anode indicates a lateral deflection of the electron beam and can be used to measure an external magnetic field. The technique is inherently temperature independent and low noise. Of the few examples of such sensors found in the literature [4]–[6], the most successful reports are from the group led by Uemura and Itoh [5], [7]. They rely on microfabrication techniques only to produce a single sharp tip, an extraction gate, and a focusing electrode. The split anode is separately mounted 5 mm away from the cathode. Despite this, their device produced extremely high sensitivities at $10\,000\%/T$.

Using conventional lithography techniques, the device can be made planar, highly sensitive (resolutions of 10–100 nT and changes in differential anode current in the range of 1000–10 000%/T are predicted by modeling [4]), and high bandwidth (electron transit time from field-emission tip to anode is around 1 ps). Other benefits include the following: ease of integration with CMOS processing, the ability to manufacture thin sensors, and fabrication of long anode–cathode distances while still retaining a thin device. For magnetic fields within about 50% of the measurable field range, the response is predicted to be linear to within a few percent [4]. There have been few examples of planar devices, although Sugiyama [8] made a lateral device on a quartz substrate which had a sensitivity of around $1000\%/T$, but this device had extremely low anode currents that were some two orders of magnitude smaller than the gate current. A more recent device produced by electron beam lithography using metallic cathode, gate, and anode structures on silicon has been reported to have a maximum sensitivity around $98\%/T$ [9].

We have previously presented the design and outlined the processing steps required to produce a planar CMOS-compatible field-emission VMS device [10]. In this brief, we report the realization of a working device with a magnetic field sensitivity of $4 \times 10^3\%/T$.

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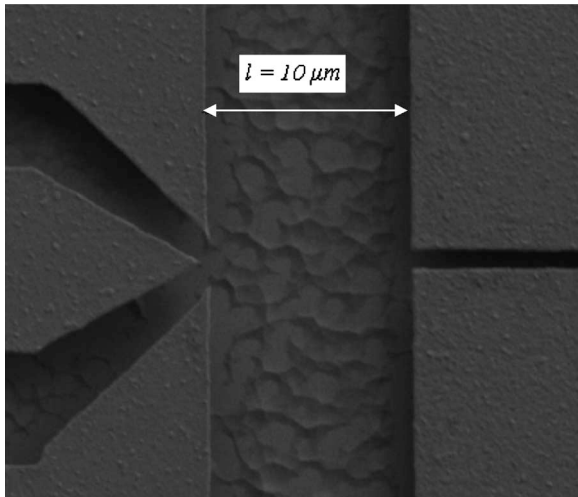


Fig. 2. SEM image of a fabricated device, showing the (LHS) cathode/gate structure and the (RHS) split anodes.

II. DEVICE DESIGN AND FABRICATION

A schematic diagram of the device is shown in Fig. 1. Cathode, gates, and anodes are all formed in silicon, separated physically and electrically from the silicon substrate by a 3- μm thermal oxide. The cathode has a very sharp tip, which acts as the field-emission tip, and two gate electrodes are placed close to this, the aperture size, tip position, and gate–cathode distance defining both the field required for electron emission and the angular divergence of the emitted electron beam. The split anodes are some distance from the cathode–gate assembly, with a gap of 500 nm between the two electrodes. The cathode–anode spacing was varied in our devices between 10 and 500 μm .

Devices were fabricated by INNOS Ltd. at Philips’ fabrication facility in Eindhoven. Wafer-bonded SOI wafers were used as substrates in order to ensure high-quality oxide layers. The top silicon layer was phosphorous doped to become heavily n-type (to a carrier concentration of 10^{20} cm^{-3}). A thin pad oxide was grown on the top silicon layer, followed by the deposition of silicon nitride, which was patterned using i-line photolithography with the outlines of the cathode tip, the gate, and the anode. LOCAL Oxidation of Silicon (LOCOS) was then used to oxidize this top silicon away in the areas where there is no nitride; the LOCOS process results in a very sharp tip at the end of the silicon cathode. Finally, the nitride was stripped in hot phosphoric acid, and then, an etch in buffered hydrofluoric acid removed the oxide surrounding the cathode tip, the split anode, and the gate to leave the completed sensor. Gold contact pads were evaporated, and individual devices were sawn from the wafer, mounted in chip carriers, and wire bonded.

Samples were mounted in a vacuum chamber, which was evacuated to 10^{-6} mbar and placed within a Helmholtz coil arrangement that permitted the application of a controlled field of up to 2.5 mT in any direction.

Measurements of the device magnetic sensitivity were performed using Keithley Instruments source–measure units (models 236 and 6430). The cathode was grounded, the gates were held at a potential of +100 V to initiate field emission, and the split anodes were held at +175 V to ensure maximum

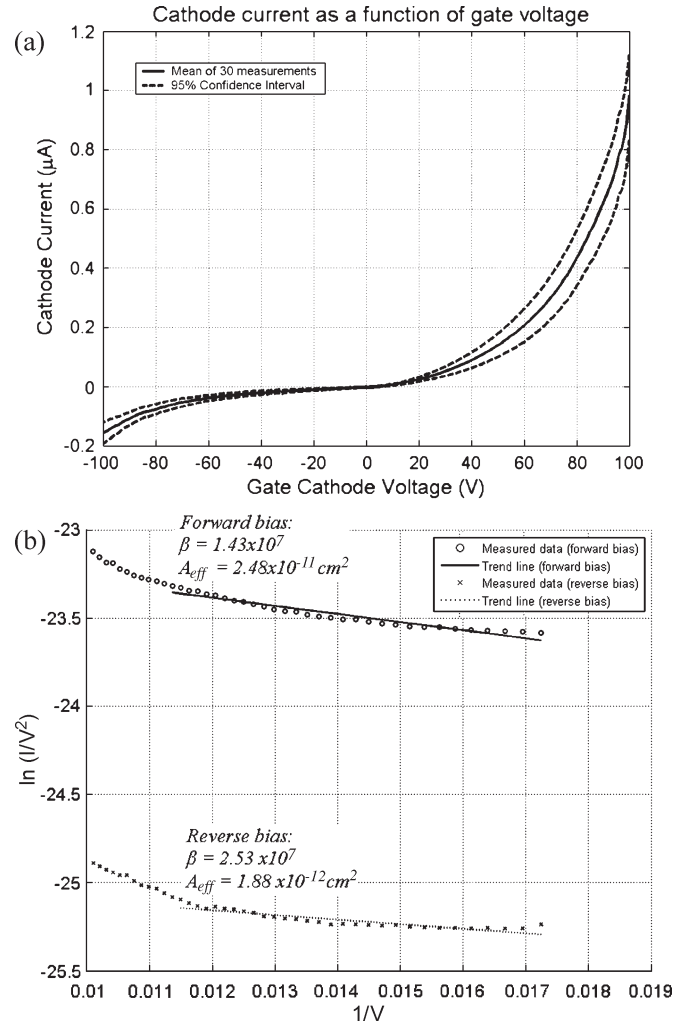


Fig. 3. (a) Gate/cathode current/voltage characteristics for a typical device. (b) Corresponding Fowler–Nordheim plots for forward- and reverse-bias cases.

current at the anodes and a low gate current (in practice, I_g was approximately 10% of the total anode current).

III. EXPERIMENTAL RESULTS

Fig. 2 shows an scanning electron microscope (SEM) image of a single device. The example shown has a cathode–anode separation of 10 μm , and the cathode tip is slightly behind the level of the gate electrodes.

Fig. 3(a) shows a current–voltage plot for the gate–cathode structure of a typical device, demonstrating field emission. Note that there is emission in both forward and reverse cathode–gate bias. In the former case, emission is from the cathode, and in the latter, it is from the gate electrodes. This is a result of the gate electrodes having sharp tips (see Fig. 2), which act as field-emission sources under reverse bias. This is not a problem for normal device operation, as VMS devices will always be operated under forward bias (positive gate voltages), and it is the anode currents that will be measured. Fig. 3(b) shows a Fowler–Nordheim plot of the data from Fig. 2a, from which both the effective cathode tip area A_{eff} and the field-emission factor β are obtained. A_{eff} values of 2.48×10^{-11}

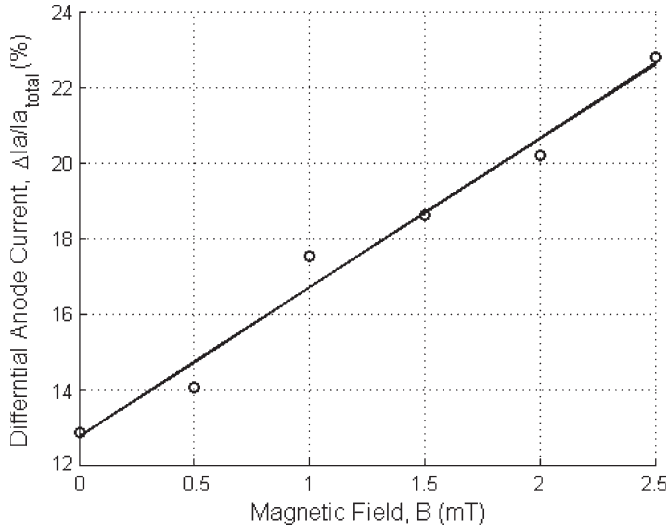


Fig. 4. Differential anode current [defined by (1)] as a function of applied magnetic field. The slope of the line gives the device sensitivity as 4000%/T.

and $1.88 \times 10^{-12} \text{ cm}^2$ were found for forward- and reverse-bias cases, respectively. These values compare favorably with other devices reported in the literature [9] and imply field-emission tip radii of approximately 28 and 8 nm, respectively. The beta values of 1.43×10^7 and 2.53×10^7 (forward- and reverse-bias cases, respectively) are a little high but, within fitting error, are consistent with the device geometry. Although there is some deviation from linear behavior at both high and low fields, this may be ascribed to Joule heating effects (high field) and threshold effects (low field). Note that only the central (linear) portion of the data was used for fitting.

Fig. 4 shows a plot of differential anode current as a function of magnetic field applied perpendicular to the plane of the device. Each point is the mean of five readings of each of the currents received by the split anodes. We define the differential anode current, where I_{a1} and I_{a2} are the currents received by the two anodes, as

$$I_d(\%) = \left| \frac{I_{a1} - I_{a2}}{I_{a1} + I_{a2}} \right| \times 100. \quad (1)$$

The slope of a plot of I_d versus B therefore yields the sensitivity of the device in units of percent per tesla. From Fig. 4, we calculate the sensitivity of our device to be $4 \times 10^3\%/T$. We note that this figure is significantly higher than that reported for similar devices in [9]. We attribute the higher sensitivity of the reported structure to a combination of improved device geometry (i.e., a longer cathode–anode distance), higher quality oxide material (SOI instead of wet oxidation), and good control of processing to ensure high-quality tips, uniform conductivity of the poly-Si layer, and low surface roughness after etching. We note that the major contributors to noise and measurement uncertainty in the present generation of devices are likely to be Joule heating of the tip at high cathode currents and tip degradation due to ion bombardment and contamination if the operating pressure is too high. Although these devices were tested at pressures around 10^{-6} mbar, they operate successfully up to pressures of 10^{-4} mbar at the expense of an increased rate

of tip degradation. Further work may concentrate on optimizing operation at higher pressures in order to relax constraints on vacuum level.

IV. CONCLUSION

We have demonstrated a field-emission vacuum magnetic sensor fabricated using standard CMOS processing techniques. The device exhibits the highest magnetic field sensitivity reported to date for a planar field-emission device: $4 \times 10^3\%/T$. This is a very promising result and suggests that this is a viable technology for the production of low-cost magnetic sensors with high sensitivity.

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